CSCI5070 Advanced Topics in Social Computing

04-Graph Mining Irwin King

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Outline

- Graph Characteristics, Patterns, and Structures
- Graph Generation & Information Propagation
- Graph Mining Algorithms



Graph Structures



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Graph Patterns

- What are the characteristics of graphs?
- How can we compare graphs?
- What patterns hold for these graphs?
 - Power laws
 - Small diameters
 - Community effects
- How does the Internet graph look like?



What Does the Web Look Like?



- Recursive bowtie structure
- Ease of navigation
- Resilience



44 million pages

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Introduction

- Graph mining is simply extraction of information from a massive graph
 - How does any network look like? The visualization of the relationship. One example is to look into how does the Internet or web look like.
 - Once we can characterize something, then we may be able to explore what is unique, abnormal, etc.
 - Are there any characteristics/principles/laws that hold?



Graph Distributions

• Two variables x and y are related by a power law when their scatter plot is linear on a log-log scale:

$$y(x) = cx^{-\gamma} \tag{1}$$

where c and γ are positive constants.

- The constant γ is often called the **power law exponent**.
- **Power Law Distribution**. A random variable is distributed according to a power law when the probability density function (pdf) is given by

$$p(x) = cx^{-\gamma}, \gamma > 1, x \ge x_{\min}$$
(2)

- $\gamma > 1$ ensures that p(x) can be normalized.
- It is unusual to find $\gamma < 1$ in nature.



Degree Distribution

- The **Degree Distribution** of an undirected graph is a plot of the count c_k of nodes with degree k, versus the degree k, typically on a log-log scale.
- Occasionally, the fraction $\frac{c_k}{N}$ is used instead of c_k ; however, this merely translates the log-log plot downwards.
- For directed graphs, out-degree and in-degree distributions are defined separately.
- Computational issues:
 - 1. Creating the scatter plot
 - 2. Computing the power law exponent
 - Regression models, maximum-likelihood estimation(MLE), nonparametric estimators, etc.
 - 3. Checking for goodness of fit
 - Correlation coefficient, statistical hypothesis methods, etc.



Examples of Power Law



- Internet graph (2.1-2.2), Internet router (2.48), in-degree (2.1) and out-degree (2.38-2.72) of the WWW graph, PageRank, citation graph (3), etc.
- Power Law distributions are *heavy-tailed* so they decay more slowly than Gaussian distributions with exponential decay!



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Other Distributions

• Exponential Cutoffs. Looks like power law over the lower range of values, but decays very fast for higher values. It is defined as,

$$y(x=k) \propto e^{-k/\kappa} k^{-\gamma}$$

where $e^{-k/\kappa}$ is the exponential cutoff term, and $k^{-\gamma}$ is the power law term.

- The airport network, electric power grid of Souther California are examples of the exponential cutoffs distribution.
- Longnormals. Sometimes subsets of a power law graph can deviate significantly. It looks like a truncated parabolas on log-log scale.
- It has unimodal distributions on the log-log scale and a discrete truncated lognormal (Discrete Gaussian Exponential, DGX) has a good fit.

$$y(x=k) = \frac{A(\mu,\sigma)}{k} \exp\left[-\frac{(\ln k - \mu)^2}{2\sigma^2}\right], k = 1, 2, \dots,$$

where μ and σ are parameters and $A(\mu, \sigma)$ is a constant.

• The topic-based subsets of the WWW, Web clickstream data, sales data in retail chains, file size distributions, and phone usages are some examples of the Longnormals distribution.



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Some Examples





Graph Characteristics

Given G, an undirected graph, N the number of nodes in G, E the number of edges in G, γ the diameter of G, d_v the outdegree of node v, and \overline{d} the average outdegree of the nodes of a graph ($\overline{d} = 2E/N$).

The outdegree, d_v , of a node v, is proportional to the rank of the node, r_v , to the power of a constant, R

$$d_v \propto r_v^R \tag{1}$$

The outdegree, d_v , of a node v, is a function of the rank of the node, r_v and the rank exponent, R, as follows

$$d_v = \frac{1}{N^{\mathcal{R}}} r_v^{\mathcal{R}} \tag{1}$$

The number of edges, E, of a graph can be estimated as a function of the number of nodes, N, and the rank exponent, \mathcal{R} , as follows:

$$E = \frac{1}{2(\mathcal{R}+1)} (1 - \frac{1}{N^{\mathcal{R}+1}})N$$



Rank Plots



Figure 3: The rank plots. Log-log plot of the outdegree d_v versus the rank r_v in the sequence of decreasing outdegree.





Figure 4: The rank plots. Log-log plot of the outdegree d_v versus the rank r_v in the sequence of decreasing outdegree.

Outdegree Plots



Figure 5: The outdegree plots: Log-log plot of frequency f_d versus the outdegree d.



The Hop Plot

- The **Hop-plot** is the plot of N_h versus h, where $N_h = \sum_u N_h(u)$, u is a node in the graph and $N_h(u)$ is the number of nodes in a neighborhood of h hops.
- The hop-plot can be used to calculate the *effective diameter* (or the eccentricity) of the graph.
- The effective diameter is defined as the minimum number of hops in which some fraction of all connected pairs of nodes can reach each other.



Clustering Coefficient

• Clustering Coefficient. Given that a node i has k_i neighbors, and there are n_i edges between the neighbors. The clustering coefficient of node i is defined as

$$C_{i} = \begin{cases} \frac{2n_{i}}{k_{i}(k_{i}-1)} & k_{i} > 1\\ 0 & k_{i} = 0 \text{ or } 1 \end{cases}$$

- For a node v with edges (u, v) and (v, w), the **Clustering Coefficient** of v measures the probability of existence of the third edge (u, w).
- The clustering coefficient of the entire graph (Global clustering coefficient) is found by averaging over all nodes in the graph.







An Example of Clustering Coefficient



Node a has 6 neighbors.

These neighbors could have been connected by 15 edges (6 x 5 / 2).

But with only 5 edges ({(c,b), (b,g), (g,f), (d,e), (d,b)}) exist so the local clustering coefficient of node a is 5/15 = 1/3

What is the global clustering coefficient?



Betweenness and Stress Plot

• **Betweenness** is a centrality measure of a vertex within a graph. It is defined as

$$C_B(v) = \sum_{s \neq v \neq t \in V} \frac{\sigma_{st}(v)}{\sigma_{st}}$$

where σ_{st} is the number of shortest paths from s to t, and $\sigma_{st}(v)$ is the number of shortest paths from s to t that pass through a vertex v.

- One can also consider all shortest paths between all pairs of nodes in a graph. The edge betweenness or stress of an edge is the number of these shortest paths that the edge belongs to and is thus a measure of the "load" on that edge.
- Stress Plot is a plot of the number of edges s_k with stress k, versus k.



Graph Generation



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Introduction

- Allows for simulation studies
- When is a generated graph realistic?
- Selected models
 - Random graph models
 - Preferential attachment models
 - Optimization-based models
 - Geographical models
 - Internet-specific models
 - BRITE, Inet, etc.



Random Graphs



- A **Random Graph** is a graph that is generated by some random process.
- A random graph is obtained by starting with a set of n vertices and adding edges between them at random.
- Different random graph models produce different probability distributions on graphs.
- The Erdös-Rényi model, denoted G(n, p) generates a random graph by having every possible edge occurs independently with probability p.
- Another model, G(n, M) assigns equal probability to all graphs with exactly M edges.
- In the G(n, M) model, a graph is chosen uniformly at random from the collection of all graphs which have n nodes and M edges.
- In the G(n, p) model, a graph is thought to be constructed by connecting nodes randomly. Each edge is included in the graph with probability p, with the presence or absence of any two distinct edges in the graph being independent.



Some Observations

- 1. If np < 1, then a graph in G(n, p) will almost surely have no connected components of size larger than $O(\log n)$.
- 2. If np = 1, then a graph in G(n, p) will almost surely have largest component whose size is of order $n^{2/3}$.
- 3. If np tends to a constant c > 1, then a graph in G(n,p) will almost surely have a unique giant component containing a positive fraction of the vertices. No other component will contain more than $O(\log n)$ vertices.
- 4. If $p < \frac{(1-\epsilon) \ln n}{n}$, then a graph in G(n, p) will almost surely contain isolated vertices.
- 5. If $p > \frac{(1+\epsilon) \ln n}{n}$, then a graph in G(n, p) will almost surely have no isolated vertices.



Scale Free Networks



- A scale-free network is a network whose degree distribution follows a power law, at least asymptotically, i.e., the fraction P(k) of nodes in the network having k connections to other nodes goes for larger values of k as P(k) ~ k^{-γ} where γ is a constant whose value is typically in the range 2 < γ < 3.
- Since it follows the power law, it decays only polynomially as $x \to \infty$, where as the Gaussian distribution has exponential decay.
- Moreover, y(x) in the power law remains unchanged to within a multiplicative factor, i.e., $y(\alpha x) = \beta y(x)$, when x is multiplied by a scaling factor.
- The functional form of the relationship remains the same for all scales.



Preferential Attachment

- Rich get richer!
- A network grows by adding vertices over time.
- The average out-degree of the graph remains at a constant value over time
- Each outgoing edge from the new vertex connects to an old vertex with a probability proportional to the indegree of the old vertex.

$$P(\text{edge to existing vertex } v) = \frac{k(v) + k_0}{\sum_i (k(i) + k_0)},$$

where k(i) represents the current in-degree of an existing node *i*, and k_0 is a constant.



Barabasi-Albert Model

- Similar to the Preferential Attachment but for undirected graph
- Two processes
 - Growth--the network adds nodes and edges over time.
 - Preferential Attachment--the probability of connecting to a node is proportional to the current degree of the node.

$$P(\text{edge to existing vertex } v) = \frac{k(v)}{\sum_i k(i)},$$

where k(i) is the degree of node *i*.



Edge Copying

- This is a community behavior that people copy links from websites that they have created.
- Three processes:
 - Node creation and deletion
 - Nodes can be created and deleted with some probability
 distribution.
 - All edges incident on the deleted nodes are also removed.



Edge Copying

- Edge creation
 - Select a node v and some edges k to add to node v
 - With probability b, these k edges are linked to nodes chosen independently and uniformly at random.
 - With probability (1 b), these edges are copied from another node
 - Choose a node *u* at random, choose *k* of its edges (*u*, *w*), and create edges (*v*, *w*).
- Edge deletion
 - Random edges can be deleted with some distribution.



Geographical (Small-World) Models

- Many real-world graphs, e.g., job seeker, six-degrees, etc., seem to have
 - Low average distance between nodes (global property)
 - High clustering coefficients (local property)
- The low average path length was being caused by weak ties joining faraway cliques.



Small World Models

• Two processes:

- Regular ring lattice (initial set-up)
 - Start with a ring lattice (N, k), a graph with N nodes set in a circle.
 Each node has k edges to its closest neighbors, with k/2 edges on each side.
- Rewriting (creating weak acquaintance edges)
 - For each node u, each of its edges (u, v) is rewired with probability p to form some different edge (u, w), where node w is chosen uniformly at random.
 - Self-loops and duplicate edges are forbidden.



The R-MAT Graph Generator

- R-MAT (Recursive MATrix) generator
 - Should match several graph patterns, e.g., power-law and other non-power-law distributions
 - Exhibit a strong community effect
 - Should generate different types of graphs, e.g., directed, undirected, weighted, bipartite, etc.
 - Should be fast parameter fitting
 - Should be efficient and scalable



R-MAT Generator

- R-MAT creates directed graphs with 2ⁿ nodes and E edges
- Procedure
 - An empty adjacency matrix
 - Divide the matrix into four equal-sized partitions
 - One partition is chosen with probabilities *a*, *b*, *c*, and *d*
 - The chosen partition is again subdivided into four smaller partitions
 - This is recursively repeated until the partition size is I
 - The above is repeated E times to generate all edges



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Discussions

- (a + b + c + d = 1) with $a \ge b, a \ge c, a \ge d$
- *a* >= *d* leads to lognormals
- The partitions *a* and *d* represent communities
- The partitions *b* and *c* are the crosslinks between groups (friends with separate preferences)
- Automatically obtain sub-communities
- Undirected graphs generated from directed graphs
- Bipartite graphs has a rectangular adjacency matrix
- Weighted graphs obtained from the hitting frequency



Information Propagation

- Propagation Attributes
 - Propagation medium
 - Propagation rate
 - State of the node
 - Connectivity patterns
- Models
 - Threshold models
 - Viral propagation models
 - Diffusion models





Viral Propagation

- SIR Model
 - Susceptible (S), Infective (I), and Removed (R)
 - Each edge (i, j) has a spreading function (birth rate) β_{ij}
 - Each Infective node *u* has a rate of getting cured (death rate) δ_u
 - The spread of infections depends on $\tau = \beta / \delta$
- SIS Model
 - Similar to the SIR model except that once an infective node is cured, it goes back to the susceptible state



Bass Diffusion Model

• The process of how new products get adopted as an interaction between users and potential users





Bass Diffusion Formulation

The **Bass Diffusion Model** is defined as

$$\frac{f(t)}{1 - F(t)} = p + qF(t)$$

where

- f(t) is the rate of change of the installed base fraction
- F(t) is the installed base fraction
- p is the coefficient of innovation
- q is the coefficient of imitation

Sales S(t) is the rate of change of installed base (i.e., adoption) f(t) multiplied by the ultimate market potential m

$$\begin{array}{lcl} S(t) &=& mf(t) \\ S(t) &=& m\frac{(p+q)^2}{p} \frac{e^{-(p+q)t}}{(1+\frac{q}{p}e^{-(p+q)t})^2} \end{array}$$

The time of peak sales t^* is defined as

$$t^* = \frac{\ln q - \ln p}{p + q}$$



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Discussions

- Properties to consider
 - Degree distributions
 - Clustering coefficient
 - Community structure
 - Implementation issues
- How do you make friends?
- How can one recommend friends?
- How does information propagate among friends?



Graph Mining



Clustering

- Finding patterns in data, or grouping similar groups of data-points together into clusters.
- Clustering algorithms for numeric data
 - Lloyd's K-means, EM clustering, spectral clustering etc.
- Traditional definition of a "good" clustering
 - Points assigned to same cluster should be highly similar
 - Points assigned to different clusters should be highly dissimilar



Graph Clustering

- Graphical representation of data as undirected graphs
- Clustering of vertices on basis of edge structure
- Defining a graph cluster
 - In its loosest sense, a graph cluster is a connected component
 - In its strictest sense, it's a maximal clique of a graph
- Many vertices within each cluster
- Few edges between clusters



GRAPH PARTITIONING!!



Clustering Paradigm

- Hierarchical clustering vs. flat clustering
- Hierarchical:
 - Top down
 - Bottom up





Overview

- Cut based methods
 - Become NP hard with introduction of size constraints
 - Approximation algorithms minimizing graph conductance
- Maximum flow
 - Using results by Golberg and Tarjan
 - Reasonable for small graphs
- Graph spectrum based methods
 - Stable perturbation analysis
 - Good even when graph is not exactly block diagonal
 - Typically, second smallest eigenvalue is taken as graph characteristic
 - Spectrum of graph transition matrix for blind walk The Chinese University of Hong Kong, CSCI5070 Advanced Topics in Social Computing, Irwin King



Graph Cuts

- Express partitioning objectives as a function of the "edge cut" of the partition
- *Cut*: Set of edges with only one vertex in a group.
 - We want to find the minimal cut between groups
 - The group that has the minimal cut would be the partition





Graph Cut Criteria

- Criterion: Minimum-cut
 - Minimize weight of connections between groups

 $\min cut(A, B)$



- Only considers external cluster connections
- Does not consider internal cluster density



Graph Cut Criteria

- Criterion: Normalized-cut [Shi & Malik,'97]
 - Consider the connectivity between groups relative to the density of each group

$$\min Ncut(A,B) = \frac{cut(A,B)}{vol(A)} + \frac{cut(A,B)}{vol(B)}$$

- Normalize the association between groups by volume
 - vol(A): The total weight of the edges originating from group A
- Why use this criterion?
 - Minimizing the normalized cut is equivalent to maximizing normalized association
 - Produce more balanced partitions



Spectral Clustering

- Algorithms that cluster points using eigenvectors of matrices derived from the data
- Obtain data representation in the low-dimensional space that can be easily clustered
- Various methods that use the eigenvectors differently



Example

- Dataset exhibits complex cluster shapes
- K-means performs very poorly in this space due bias toward dense spherical clusters





 In the embedded space given by two leading eigenvectors, clusters are trivial to separate



Spectral Graph Theory

- Possible approach
 - Represent a similarity graph as a matrix
 - Apply knowledge from Linear Algebra...
- The eigenvalues and eigenvectors
- Spectral Graph Theory
- of a matrix provide global information about its structure. Spectral Graph Theory $\begin{bmatrix} w_{11} & K & w_{1n} \\ M & M \\ w_{n1} & K & w_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ M \\ M \\ x_n \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ M \\ X_n \end{bmatrix}$
 - Analyze the "spectrum" of matrix representing a graph
 - Spectrum: The eigenvectors of a graph, ordered by the magnitude(strength) of their corresponding eigenvalues

$$\Lambda = \{\lambda_1, \lambda_2, \dots, \lambda_n\}$$



Spectral Clustering Algorithms

- Three basic stages
 - Pre-processing
 - Construct a matrix representation of the dataset
 - Decomposition
 - Compute eigenvalues and eigenvectors of the matrix
 - Map each point to a lower-dimensional representation based on one or more eigenvectors
 - Grouping
 - Assign points to two or more clusters, based on the new representation



K-Way Spectral Clustering

- How do we partition a graph into k clusters?
- Two basic approaches
 - **Recursive bi-partitioning** [Hagen et al., '91]
 - Recursively apply bi-partitioning algorithm in a hierarchical divisive manner
 - Disadvantages: Inefficient, unstable

• **Cluster multiple eigenvectors** [Shi & Malik, '00]

- Build a reduced space from multiple eigenvectors
- Commonly used in recent papers
- A preferable approach...but it's like doing PCA and then k-means



Recursive Bi-partitioning

- Partition using only one eigenvector at a time
- Use procedure recursively
- Example: Image Segmentation
 - Uses 2nd (smallest) eigenvector to define optimal cut
 - Recursively generates two clusters with each cut



K-eigenvector Clustering

- K-eigenvector Algorithm [Ng et al., '01]
- Pre-processing
 - Construct the scaled adjacency matrix

$$A' = D^{-1/2} A D^{-1/2}$$

- Decomposition
 - Find the eigenvalues and eigenvectors of A'
 - Build embedded space from the eigenvectors corresponding to the k largest eigenvalues

• Grouping

Apply k-means to reduced n x k space to produce k clusters



Summary

- Clustering as a graph partitioning problem
 - Quality of a partition can be determined using graph cut criteria
 - Identifying an optimal partition is NP-hard
- Spectral clustering techniques
 - Efficient approach to calculate near-optimal bi-partitions and k-way partitions
 - Based on well-known cut criteria and strong theoretical background



Graph Cuts and Max-Flow/Min-Cut Algorithms

- A **flow network** is defined as a **directed graph** where an edge has a **nonnegative capacity**
- A **flow** in G is a real-valued (often integer) function that satisfies the following three properties:
 - Capacity Constraint:

• For all
$$u, v \in V, f(u, v) \leq c(u, v)$$

- Skew Symmetry
 - For all $u, v \in V, f(u, v) = -f(v, u)$
- Flow Conservation

• For all
$$u \in (V \setminus \{s, t\}), \sum_{v \in V} f(u, v) = 0$$



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 $v \in V$

How to Find the Minimum Cut?

• Theorem: In graph G, the maximum source-to-sink flow possible is equal to the capacity of the minimum cut in G

[L. R. Foulds, Graph Theory Applications, 1992 Springer-Verlag New York Inc., 247-248]



Maximum Flow and Minimum Cut Problem

- Some basic concepts
 - If f is a flow, then the net flow across the cut (S, T) is defined to be f(S, T), which is the sum of all edge capacities from S to T subtracted by the sum of all edge capacities from T to S
 - The capacity of the cut (S, T) is c(S, T), which is the sum of the capacities of all edge from S to T
 - A minimum cut is a cut whose capacity is the minimum over all cuts of *G*
- Algorithms
 - Ford-Fulkerson Algorithm
 - Push-Relabel Algorithm
 - New Algorithm by Boykov, etc.



Ford-Fulkerson Algorithm

- Main Operation
 - Starting from zero flow, increase the flow gradually by finding a path from s to t along which more flow can be sent, until a max-flow is achieved
 - The path for flow to be pushed through is called an **augmenting path**
- The Ford-Fulkerson algorithm uses a residual network of flow in order to find the solution
- The residual network is defined as the network of edges containing flow that has already been sent
- For example, in the graph shown below, there is an initial path from the source to the sink, and the middle edge has a total capacity of 3, and a residual capacity of 3-1=2



Ford-Fulkerson Algorithm

• Assuming there are two vertices, u and v, let f(u, v) denote the flow between them, c(u, v) be the total capacity, $c_f(u, v)$ be the residual capacity, and there should be,

$$c_f(u,v) = c(u,v) - f(u,v)$$

- Given a flow network and a flow f, the residual network of G is $G_f = (V, E_f)$, where $E_f = \{(u, v) \in V \times V : c_f(u, v) > 0\}$
- Given a flow network and a flow f, an augmenting path P is a simple path from s to t in the residual network
- We call the maximum amount by which we can increase the flow on each edge in an augmenting path P the residual capacity of P, given by,

$$c_f(P) = \min\{c_f(u, v) : (u, v) \text{ is on } P\}$$

Example













Finding the Min-Cut

• After the max-flow is found, the minimum cut is determined by

$$S = \{ \text{All vertices reachable from } s \}$$
$$T = G \backslash S$$





Special Case

• As in some applications only undirected graph is constructed, when we want to find the min-cut, we assign two edges with the same capacity to take the place of the original undirected edge





Ford-Fulkerson Algorithm Analysis

- The running time of the algorithm depends on how the augmenting path is determined
 - If the searching for augmenting path is realized by a breadthfirst search, the algorithm runs in polynomial time of $O(E | f_{max} |)$
- Under some extreme cases the efficiency of the algorithm can be reduced drastically
 - One example is shown in the figure below, applying Ford-Fulkerson algorithm needs 400 iterations to get the max flow of 400





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Small-World Phenomenon

- We are all linked by short chains of acquaintances, or "six degrees of separation"
- An abundance of short paths in a social network graph
- Started by a Social Psychologist Stanley Milgram in the 1960s with two important discoveries
 - The existence of short paths among people
 - People in society, with knowledge of only their own personal acquaintances, were collectively able to forward the letter to a distant target so quickly
- The power of an effective routing algorithm--equipped with purely local information, to find efficient paths to a destination; that such a decentralized routing scheme is effective



Watts and Strogatz

- Highly clustered sub-network consisting of the "local acquaintances" of nodes
- A collection of random long-range shortcuts
- Start with a d-dimensional lattice network, and add a small number of long-range links out of each node, to destinations chosen uniformly at random
- In the model of a d-dimensional lattice with uniformly random shortcuts, no decentralized algorithm can find short paths (so short paths exist, but local knowledge does not suffice to construct them!)
- However, add links between nodes of this network with a probability that decays like the *d*-th power of their distance (in *d* dimensions). It is quite useful in P2P networks in sharing local information for decentralized searching.









Traditional Information Retrieval

- Content matching against the query
 - Occurrence of query words
 - Location of query words
 - Document weighting
- Not much of ranking
- Science Citation Index and Impact Factor



Challenges of Web Search

• Voluminous

- Dynamic (generated deep web)
- Self-organized
- Hyperlinked
- Quality of Information
- Accessibility



Information Retrieval and Search Engine





Crawler

- Page Repository
- Indexing Module
- Indices

- Query Module
- Ranking Module



Information Retrieval Basics

- Vector Space Model
- Relevance Scoring and Relevance Feedback
- Meta-search Engines
- Precision vs. Recall


The InDegree Algorithm

- A simple heuristic
- Rank the pages according to popularity (indegree) of the page
- Issues?



The PageRank Algorithm

- Hyperlinked documents are different!
 - Similar to academic papers
 - In-links = authorities
 - Out-links = citations
 - Citations give better approximation of the quality of pages



Define PageRank

The PageRank calculation is defined as follows. We assume page A has pages T_1, \dots, T_n which point to it (i.e., are citations). The parameter d is a damping factor which can be set between 0 and 1. C(A) is defined as the number of links going out of page A. The PageRank of a page A is given as follows:

$$PR(A) = (1 - d) + d(PR(T_1)/C(T_1) + \dots + PR(T_n)/C(T_n)).$$
(1)
$$PR(A) = (1 - d) + d\sum_{i=1}^{n} \frac{PR(T_i)}{C(T_i)}.$$

- PageRanks form a probability distribution over web pages, so the sum of all web pages' PageRanks will be one
- It can be calculated using a simple iterative algorithm, and corresponds to the principal eigenvector of the normalized link matrix of the web



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Assumptions

- A "random surfer" who is given a web page at random
- The surfer keeps clicking on links, never hitting "back"
- The surfer gets bored and starts on another random page
- The probability that the random surfer visits a page is its PageRank
- The *d* damping factor is the probability at each page the Surfer will get bored and request another random page.
- Instead of a global d, one may consider a page damping factor d_i for each individual page or a group of pages





$$PR(A) = 14/13 = 1.07692308$$

 $PR(B) = 10/13 = 0.76923077$
 $PR(C) = 15/13 = 1.15384615$

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(4)

(5)

(6)

Kleinberg's Algorithm

- Web page importance should depend on the search query being performed
- Each page should have a separate "authority" rating (based on the links going to the page) that captures the quality of the page as a resource itself
- Each page should also have a "hub" rating (based on the links going from the page) that captures the quality of the pages as a pointer to useful resources



Hubs Authorities



Define HITS Algorithm

- The HITS (Hyperlink Induced Topic Distillation) algorithm computes lists of hubs and authorities for WWW search topics
- Start with a search topic, specified by one or more query terms
 - Sampling Stage--constructs a focused collection of several thousand Web pages likely to be rich in relevant authorities
 - Weight-propagation Stage-- determines numerical estimates of hub and authority weights by an iterative procedure
- The pages with the highest weights are returned as hubs and authorities for the search topic



The HITS Algorithm

Let the Web be a digraph G = (V, E). Given a subgraph $S \subseteq V$ with $u, v \in S$ and $(u, v) \in E$. The authority and hub weights are updated as follows.

1. If a page is pointed to by many good hubs, we would like to increase its authority weight.

$$x_p = \sum_{\substack{q \text{ such that } q \to p}} y_q, \tag{1}$$

where the notation $q \rightarrow p$ indicates that q links to p.

2. If a page points to many good authorities, we increase its hub weight

$$y_p = \sum_{\substack{q \text{ such that } p \to q}} x_q. \tag{2}$$

The above can be rewritten in a matrix notation as

$$x \leftarrow A^T y \leftarrow A^T A x = (A^T A) x \tag{3}$$

and

$$y \leftarrow Ax \leftarrow AA^T y = (AA^T)y$$

The Chinese University of Hong Kong, CSCI5070 Advanced Topics in Social Computing, Irwin King



The HITS Pseudocode

- It is executed at query time, not at indexing time
- The hub and authority scores assigned to a page are query-specific.
- It computes two scores per document, hub and authority, as opposed to a single score.
- It is processed on a small subset of 'relevant' documents, not all documents as was the case with PageRank.

```
1 G := set of pages
 2 for each page p in G do
    p.auth = 1 // p.auth is the authority score of the page p
     p.hub = 1 // p.hub is the hub score of the page p
 5 function HubsAndAuthorities(G)
     for step from 1 to k do // run the algorithm for k steps
 6
       for each page p in G do // update all authority values first
 7
 8
         for each page q in p.incomingNeighbors do // p.incomingNeighbors is the set of pages that link to p
           p.auth += q.hub
 9
       for each page p in G do // then update all hub values
10
11
         for each page r in p.outgoingNeighbors do // p.outgoingNeighbors is the set of pages that p links to
           p.hub += r.auth
12
```

